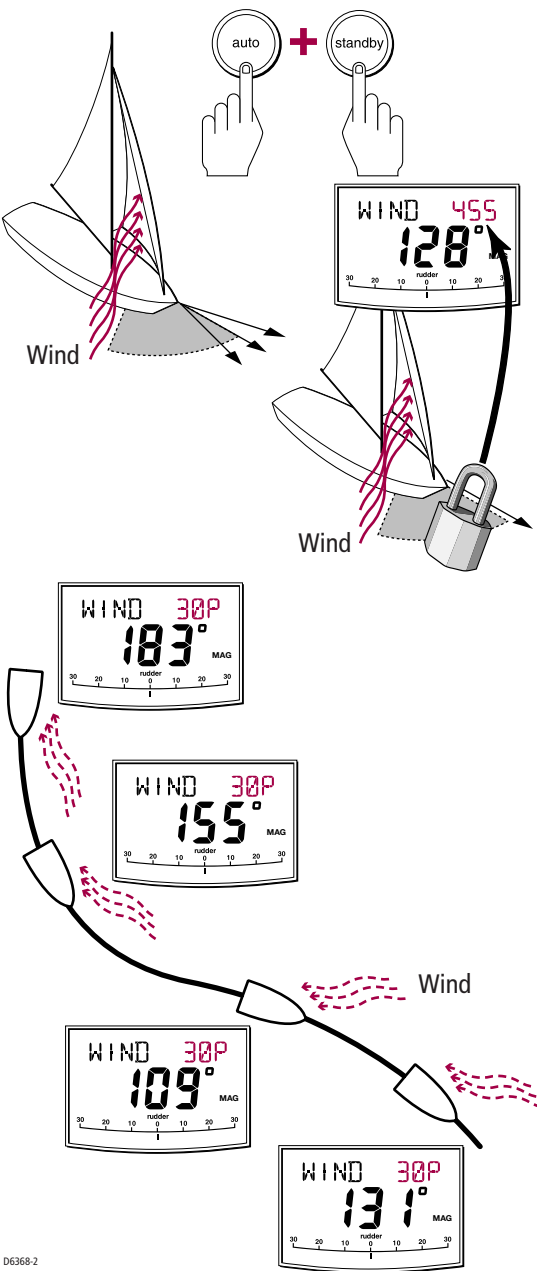
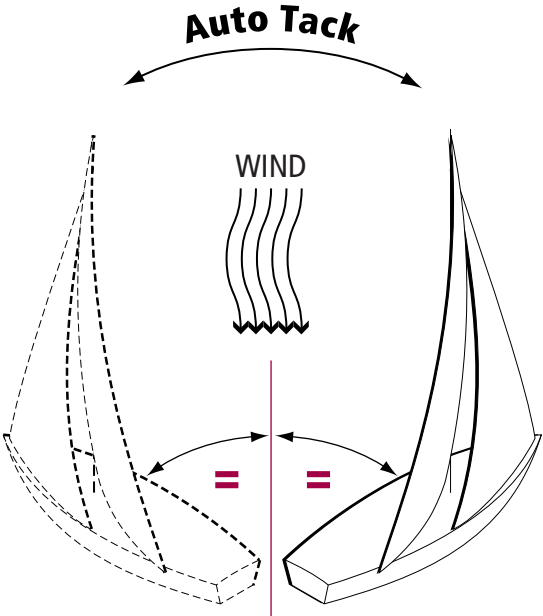


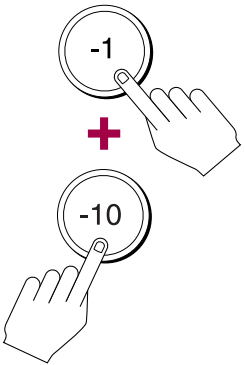
To Automatically Steer to a Fixed Wind Angle



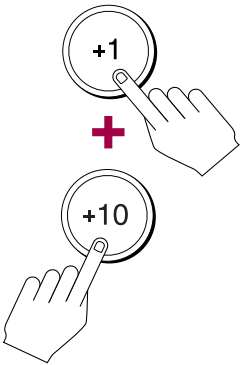
Autotack



Auto Tack
PORT



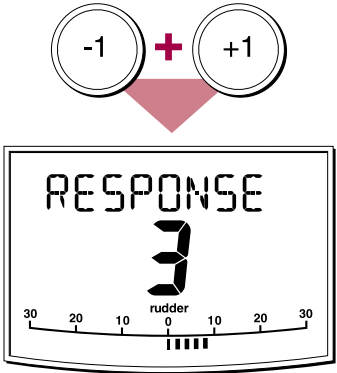
Auto Tack
STARBOARD



N.B. Refer to section 1.5 of the ST6002 Operating Guide for full details

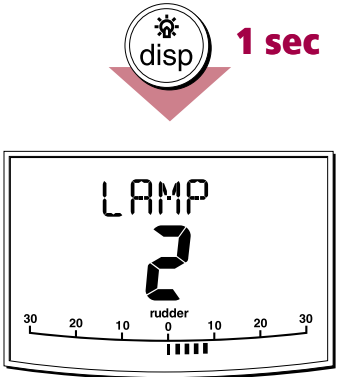
To Adjust Autopilot Course-keeping Accuracy

Autopilot response controls course keeping accuracy. Higher response settings keep a tighter course but increase the amount of drive activity and battery use. Set to a level appropriate for your needs



Use **-1** or **+1** to adjust response level. Press **disp** to return to previous mode.

To Adjust Lighting Level



Use **disp** to adjust lighting level. Wait 10 sec to return to previous mode.

Raymarine®

SmartPilot®
ST6002 Controller



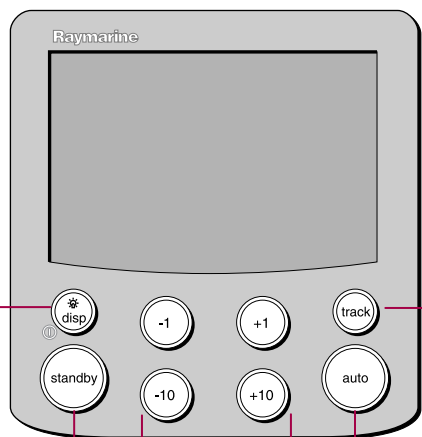
Quick Start Guide

Display Layout

To activate the Autopilot

To change the Autopilot Heading

To follow a Route set on a Chartplotter



standby
Press for
Manual Control

auto
Press to activate
the Autopilot

course change keys

Port 1° Starboard 1°
Port 10° Starboard 10°

track

When the Autopilot
is activated, press
to follow a route
from a connected
navigation system.

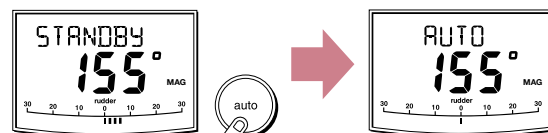
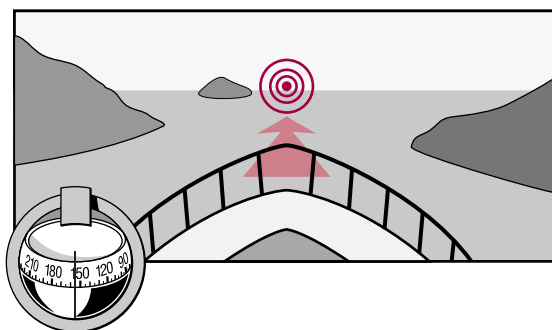
Press again to accept
the new course

disp

Press to display
data pages

Press for 1 second
for lamp control

Press for 3 seconds
for power off



For Manual Control

